

# Package: tiledbsoma (via r-universe)

August 29, 2024

**Type** Package

**Title** 'TileDB' Stack of Matrices, Annotated ('SOMA')

**Description** Interface for working with 'TileDB'-based Stack of Matrices, Annotated ('SOMA'): an open data model for representing annotated matrices, like those commonly used for single cell data analysis. It is documented at <<https://github.com/single-cell-data>>; a formal specification available is at <[https://github.com/single-cell-data/SOMA/blob/main/abstract\\_specification.md](https://github.com/single-cell-data/SOMA/blob/main/abstract_specification.md)>.

**Version** 1.8.1

**URL** <https://github.com/single-cell-data/TileDB-SOMA>

**BugReports** <https://github.com/single-cell-data/TileDB-SOMA/issues>

**License** MIT + file LICENSE

**Encoding** UTF-8

**Depends** R (>= 4.0.0)

**Imports** R6, methods, Matrix, stats, bit64, tiledb (>= 0.24.0), tiledb (<= 0.24.99), arrow, utils, fs, glue, urltools, Rcpp, data.table, spdl, rlang, tools, tibble

**LinkingTo** Rcpp, RcppSpdlog, RcppInt64

**Additional\_repositories** <https://ghrr.github.io/drat>

**Roxygen** list(markdown = TRUE)

**RoxygenNote** 7.2.3

**Suggests** rmarkdown, knitr, withr, testthat (>= 3.0.0), pbmc3k.tiledb, pbmc3k.sce, SeuratObject (>= 4.1.0), datasets, SingleCellExperiment (>= 1.20.0), SummarizedExperiment (>= 1.28.0), S4Vectors, jsonlite

**VignetteBuilder** knitr

**Config/testthat.edition** 2

**OS\_type** unix

**SystemRequirements** cmake, git

**Repository** <https://mojaveazure.r-universe.dev>

**RemoteUrl** <https://github.com/single-cell-data/TileDB-SOMA>

**RemoteRef** ph/test/doublepin

**RemoteSha** 9f8ed9555a0dec364887dc5d4fe54931aa47728d

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**ConfigList***A Configuration List*

---

**Description**

An R6 mapping type for configuring various “parameters”. Essentially, serves as a nested map where the inner map is a [ScalarMap](#): {<param>: {<key>: <value>}}

**Super class**

[tiledbsoma::MappingBase](#) -> ConfigList

**Methods****Public methods:**

- [ConfigList\\$get\(\)](#)
- [ConfigList\\$set\(\)](#)
- [ConfigList\\$setv\(\)](#)
- [ConfigList\\$clone\(\)](#)

**Method get():**

*Usage:*

ConfigList\$get(param, key = NULL, default = quote(expr = ))

*Arguments:*

param Outer key or “parameter” to fetch

key Inner key to fetch; pass NULL to return the [map](#) for param

default Default value to fetch if key is not found; defaults to NULL

*Returns:* The value of key for param in the map, or default if key is not found

**Method set():**

*Usage:*

ConfigList\$set(param, key, value)

*Arguments:*

param Outer key or “parameter” to set

key Inner key to set

value Value to add for key, or NULL to remove the entry for key; optionally provide only param and value as a [ScalarMap](#) to update param with the keys and values from value

*Returns:* \[chainable\] Invisibly returns self with value added for key in param

**Method setv():**

*Usage:*

ConfigList\$setv(...)

*Arguments:*

... Ignored

*Returns:* Nothing; setv() is disabled for ConfigList objects

**Method** clone(): The objects of this class are cloneable with this method.

*Usage:*

ConfigList\$clone(deep = FALSE)

*Arguments:*

deep Whether to make a deep clone.

## Description

Access example SOMA objects bundled with the tiledbsoma package.

Use list\_datasets() to list the available datasets and load\_dataset() to load a dataset into memory using the appropriate SOMA class. The extract\_dataset() method returns the path to the extracted dataset without loading it into memory.

## Usage

```
list_datasets()

extract_dataset(name, dir = tempdir())

load_dataset(name, dir = tempdir(), tiledbsoma_ctx = NULL)
```

## Arguments

name	The name of the dataset.
dir	The directory where the dataset will be extracted to (default: tempdir()).
tiledbsoma_ctx	Optional TileDB ‘Context’ object, defaults to NULL

## Details

The SOMA objects are stored as tar.gz files in the package’s extdata directory. Calling load\_dataset() extracts the tar.gz file to the specified dir, inspects its metadata to determine the appropriate SOMA class to instantiate, and returns the SOMA object.

## Value

- list\_datasets() returns a character vector of the available datasets.
- extract\_dataset() returns the path to the extracted dataset.
- load\_dataset() returns a SOMA object.

## Examples

```
soma_pbmc_small <- load_dataset("soma-exp-pbmc-small")
```

---

**matrixZeroBasedView**    *matrixZeroBasedView is a wrapper shim for a matrix or Matrix::sparseMatrix providing*

---

## Description

`matrixZeroBasedView` is a class that allows elemental matrix access using zero-based indeces.

## Methods

### Public methods:

- `matrixZeroBasedView$new()`
- `matrixZeroBasedView$take()`
- `matrixZeroBasedView$dim()`
- `matrixZeroBasedView$nrow()`
- `matrixZeroBasedView$ncol()`
- `matrixZeroBasedView$get_one_based_matrix()`
- `matrixZeroBasedView$sum()`
- `matrixZeroBasedView$print()`
- `matrixZeroBasedView$clone()`

**Method** `new()`: Initialize (lifecycle: experimental)

*Usage:*

```
matrixZeroBasedView$new(x)
```

*Arguments:*

x `matrix` or `Matrix::sparseMatrix` or `Matrix::Matrix`

**Method** `take()`: Zero-based matrix element access

*Usage:*

```
matrixZeroBasedView$take(i = NULL, j = NULL)
```

*Arguments:*

i Row index (zero-based).

j Column index (zero-based).

*Returns:* The specified matrix slice as another `matrixZeroBasedView`

**Method** `dim()`: dim

*Usage:*

```
matrixZeroBasedView$dim()
```

*Returns:* The dimensions of the matrix.

**Method** `nrow()`: `nrow`

*Usage:*

```
matrixZeroBasedView$nrow()
```

*Returns:* Matrix row count.

**Method** `ncol()`: `ncol`

*Usage:*

```
matrixZeroBasedView$ncol()
```

*Returns:* Matrix column count.

**Method** `get_one_based_matrix()`: Get the one-based R matrix with its original class

*Usage:*

```
matrixZeroBasedView$get_one_based_matrix()
```

*Returns:* One-based matrix

**Method** `sum()`: Perform arithmetic sum between this `linkmatrixZeroBasedView` and another `linkmatrixZeroBasedView`.

*Usage:*

```
matrixZeroBasedView$sum(x)
```

*Arguments:*

`x` the `linkmatrixZeroBasedView` to sum.

*Returns:* The result of the sum as a `matrixZeroBasedView`.

**Method** `print()`: `print`

*Usage:*

```
matrixZeroBasedView$print()
```

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

```
matrixZeroBasedView$clone(deep = FALSE)
```

*Arguments:*

`deep` Whether to make a deep clone.

---

PlatformConfig	<i>Platform Configuration</i>
----------------	-------------------------------

---

**Description**

An R6 mapping type for configuring various “parameters” for multiple “platforms”, essentially serves a multi-nested map where the inner map is a [ScalarMap](#) contained within a [ConfigList](#) (middle map): {platform: {param: {key: value}}}

**Super class**

[tiledbsoma::MappingBase](#) -> PlatformConfig

**Methods****Public methods:**

- [PlatformConfig\\$platforms\(\)](#)
- [PlatformConfig\\$params\(\)](#)
- [PlatformConfig\\$get\(\)](#)
- [PlatformConfig\\$get\\_params\(\)](#)
- [PlatformConfig\\$set\(\)](#)
- [PlatformConfig\\$setv\(\)](#)
- [PlatformConfig\\$clone\(\)](#)

**Method platforms():**

*Usage:*

PlatformConfig\$platforms()

*Returns:* The names of the “platforms” (outer keys)

**Method params():**

*Usage:*

PlatformConfig\$params(platform = NULL)

*Arguments:*

platform The “platform” to pull parameter names (middle keys) for; pass TRUE to return all possible parameter names

*Returns:* The parameter names (middle keys) for platform

**Method get():**

*Usage:*

```
PlatformConfig$get(  
  platform,  
  param = NULL,  
  key = NULL,  
  default = quote(expr = )  
)
```

*Arguments:*

`platform` The name of the “platform” (outer key) to fetch  
`param` The name of the “paramters” of `platform` to fetch; if NULL, returns the [configuration](#) for `platform`  
`key` The “key” (inner key) for `param` in `platform` to fetch; if NULL and `param` is passed, returns the [map](#) for `param` in `platform`  
`default` Default value to fetch if key is not found; defaults to null

*Returns:* The value of `key` for `param` in `platform` in the map, or `default` if `key` is not found

**Method** get\_params():*Usage:*

```
PlatformConfig$get_params(platform)
```

*Arguments:*

`platform` The name of the “platform” (outer key) to fetch

*Returns:* The [ConfigList](#) for `platform`

**Method** set():*Usage:*

```
PlatformConfig$set(platform, param, key, value)
```

*Arguments:*

`platform` The name of the “platform” (outer key) to set  
`param` Name of the “parameter” (middle key) in `platform` to set  
`key` Inner key to set  
`value` Value to add for `key`, or NULL to remove the entry for `key`; optionally provide only `platform`, `param`, and `value` as a [ScalarMap](#) to update `param` for `platform` with the keys and values from `value`

*Returns:* \[chainable\] Invisibly returns `self` with `value` added for `key` in `param` for `platform`

**Method** setv():*Usage:*

```
PlatformConfig$setv(...)
```

*Arguments:*

... Ignored

*Returns:* Nothing; `setv()` is disabled for `PlatformConfig` objects

**Method** clone(): The objects of this class are cloneable with this method.*Usage:*

```
PlatformConfig$clone(deep = FALSE)
```

*Arguments:*

`deep` Whether to make a deep clone.

---

`set_log_level`      *Set the logging level for the R package and underlying C++ library*

---

## Description

Set the logging level for the R package and underlying C++ library

## Usage

```
set_log_level(level)
```

## Arguments

`level`      A character value with logging level understood by ‘spdlog’ such as “trace”, “debug”, “info”, or “warn”.

## Value

Nothing is returned as the function is invoked for the side-effect.

---

`show_package_versions`    *Display package versions*

---

## Description

Print version information for **tiledb** (R package), libtiledbsoma, and TileDB embedded, suitable for assisting with bug reports.

## Usage

```
show_package_versions()
```

---

SOMAAxisQuery

*SOMA Axis Query*

---

## Description

Construct a single-axis query object with a combination of coordinates and/or value filters for use with [SOMAExperimentAxisQuery](#). (lifecycle: experimental)

Per dimension, the SOMAAxisQuery can have value of:

- None (i.e., coords = NULL and value\_filter = NULL) - read all values
- Coordinates - a set of coordinates on the axis dataframe index, expressed in any type or format supported by [SOMADataFrame](#)'s read() method.
- A SOMA value\_filter across columns in the axis dataframe, expressed as string
- Or, a combination of coordinates and value filter.

## Public fields

coords The coordinates for the query.

value\_filter The value filter for the query.

## Methods

### Public methods:

- [SOMAAxisQuery\\$new\(\)](#)
- [SOMAAxisQuery\\$clone\(\)](#)

**Method new():** Create a new SOMAAxisQuery object.

*Usage:*

SOMAAxisQuery\$new(value\_filter = NULL, coords = NULL)

*Arguments:*

value\_filter Optional string containing a logical expression that is used to filter the returned values.

coords Optional indices specifying the rows to read: either a vector of the appropriate type or a named list of vectors corresponding to each dimension.

**Method clone():** The objects of this class are cloneable with this method.

*Usage:*

SOMAAxisQuery\$clone(deep = FALSE)

*Arguments:*

deep Whether to make a deep clone.

## See Also

[tiledb::parse\\_query\\_condition\(\)](#) for more information about valid value filters.

---

SOMAAxisQueryResult      SOMAExperiment Axis Query Result

---

## Description

Access [SOMAExperimentAxisQuery](#) results.

## Active bindings

`obs` [arrow::Table](#) containing obs query slice.

`var` [arrow::Table](#) containing var query slice. `measurement_name`.

`X_layers` named list of [arrow::Tables](#) for each X layer.

## Methods

### Public methods:

- [SOMAAxisQueryResult\\$new\(\)](#)
- [SOMAAxisQueryResult\\$clone\(\)](#)

**Method** `new()`: Create a new SOMAAxisQueryResult object.

*Usage:*

`SOMAAxisQueryResult$new(obs, var, X_layers)`

*Arguments:*

`obs, var` [arrow::Table](#) containing obs or var query slice.

`X_layers` named list of [arrow::Tables](#), one for each X layer.

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

`SOMAAxisQueryResult$clone(deep = FALSE)`

*Arguments:*

`deep` Whether to make a deep clone.

---

SOMACollection

*SOMA Collection*

---

## Description

Contains a key-value mapping where the keys are string names and the values are any SOMA-defined foundational or composed type, including [SOMACollection](#), [SOMADataFrame](#), [SOMADenseNDArray](#), [SOMASparseNDArray](#), or [SOMAExperiment](#). (lifecycle: experimental)

## Super classes

[tiledbsoma::TileDBObject](#) -> [tiledbsoma::TileDBGroup](#) -> [tiledbsoma::SOMACollectionBase](#)  
-> SOMACollection

## Methods

### Public methods:

- [SOMACollection\\$clone\(\)](#)

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

`SOMACollection$clone(deep = FALSE)`

*Arguments:*

`deep` Whether to make a deep clone.

---

SOMACollectionCreate

*Create SOMA Collection*

---

## Description

Factory function to create a SOMADataFrame for writing, (lifecycle: experimental)

## Usage

```
SOMACollectionCreate(  
  uri,  
  platform_config = NULL,  
  tiledbsoma_ctx = NULL,  
  tiledb_timestamp = NULL  
)
```

**Arguments**

```
uri           URI for the TileDB object
platform_config
             Optional platform configuration
tiledbsoma_ctx  Optional SOMATileDBContext
tiledb_timestamp
             Optional Datetime (POSIXct) for TileDB timestamp
```

---

SOMACollectionOpen    *Open SOMA Collection*

---

**Description**

Factory function to open a SOMACollection for reading, (lifecycle: experimental)

**Usage**

```
SOMACollectionOpen(
  uri,
  mode = "READ",
  platform_config = NULL,
  tiledbsoma_ctx = NULL,
  tiledb_timestamp = NULL
)
```

**Arguments**

```
uri           URI for the TileDB object
mode          One of "READ" or "WRITE"
platform_config
             Optional platform configuration
tiledbsoma_ctx optional SOMATileDBContext
tiledb_timestamp
             Optional Datetime (POSIXct) for TileDB timestamp. In READ mode, defaults
             to the current time. If non-NULL, then all members accessed through the col-
             lection object inherit the timestamp.
```

SOMADataFrame

*SOMADataFrame*

## Description

`SOMADataFrame` is a multi-column table that must contain a column called `soma_joinid` of type `int64`, which contains a unique value for each row and is intended to act as a join key for other objects, such as [SOMASparseNDArray](#). (lifecycle: experimental)

## Super classes

```
tiledbsoma::TileDBObject -> tiledbsoma::TileDBArray -> tiledbsoma::SOMAArrayBase -> SOMADataFrame
```

## Methods

### Public methods:

- [SOMADataFrame\\$create\(\)](#)
- [SOMADataFrame\\$write\(\)](#)
- [SOMADataFrame\\$read\(\)](#)
- [SOMADataFrame\\$update\(\)](#)
- [SOMADataFrame\\$clone\(\)](#)

**Method** `create()`: Create (lifecycle: experimental)

*Usage:*

```
SOMADataFrame$create(  
  schema,  
  index_column_names = c("soma_joinid"),  
  platform_config = NULL,  
  internal_use_only = NULL  
)
```

*Arguments:*

`schema` an [arrow::schema](#).

`index_column_names` A vector of column names to use as user-defined index columns. All named columns must exist in the schema, and at least one index column name is required.

`platform_config` A [platform configuration](#) object

`internal_use_only` Character value to signal this is a 'permitted' call, as `create()` is considered internal and should not be called directly.

**Method** `write()`: Write (lifecycle: experimental)

*Usage:*

```
SOMADataFrame$write(values)
```

*Arguments:*

`values` An [arrow::Table](#) or [arrow::RecordBatch](#) containing all columns, including any index columns. The schema for values must match the schema for the SOMADataFrame.

**Method `read()`:** Read (lifecycle: experimental) Read a user-defined subset of data, addressed by the dataframe indexing column, and optionally filtered.

*Usage:*

```
SOMADataFrame$read(
  coords = NULL,
  column_names = NULL,
  value_filter = NULL,
  result_order = "auto",
  iterated = FALSE,
  log_level = "auto"
)
```

*Arguments:*

`coords` Optional named list of indices specifying the rows to read; each (named) list element corresponds to a dimension of the same name.

`column_names` Optional character vector of column names to return.

`value_filter` Optional string containing a logical expression that is used to filter the returned values. See [tiledb::parse\\_query\\_condition](#) for more information.

`result_order` Optional order of read results. This can be one of either "ROW\_MAJOR", "COL\_MAJOR", or "auto" (default).

`iterated` Option boolean indicated whether data is read in call (when FALSE, the default value) or in several iterated steps.

`log_level` Optional logging level with default value of "warn".

*Returns:* [arrow::Table](#) or [TableReadIter](#)

**Method `update()`:** Update (lifecycle: experimental)

*Usage:*

```
SOMADataFrame$update(values, row_index_name = NULL)
```

*Arguments:*

`values` A `data.frame`, [arrow::Table](#), or [arrow::RecordBatch](#).

`row_index_name` An optional scalar character. If provided, and if the `values` argument is a `data.frame` with row names, then the row names will be extracted and added as a new column to the `data.frame` prior to performing the update. The name of this new column will be set to the value specified by `row_index_name`.

*Details:* Update the existing SOMADataFrame to add or remove columns based on the input:

- columns present in the current the SOMADataFrame but absent from the new values will be dropped
- columns absent in current SOMADataFrame but present in the new values will be added
- any columns present in both will be left alone, with the exception that if values has a different type for the column, the entire update will fail because attribute types cannot be changed.

Furthermore, `values` must contain the same number of rows as the current SOMADataFrame.

**Method clone():** The objects of this class are cloneable with this method.

*Usage:*

```
SOMADataFrame$clone(deep = FALSE)
```

*Arguments:*

`deep` Whether to make a deep clone.

SOMADataFrameCreate     *Create SOMA DataFrame*

## Description

Factory function to create a SOMADataFrame for writing, (lifecycle: experimental)

## Usage

```
SOMADataFrameCreate(  
  uri,  
  schema,  
  index_column_names = c("soma_joinid"),  
  platform_config = NULL,  
  tiledbsoma_ctx = NULL,  
  tiledb_timestamp = NULL  
)
```

## Arguments

<code>uri</code>	URI for the TileDB object
<code>schema</code>	schema Arrow schema argument passed on to DataFrame\$create()
<code>index_column_names</code>	Index column names passed on to DataFrame\$create()
<code>platform_config</code>	Optional platform configuration
<code>tiledbsoma_ctx</code>	Optional SOMATileDBContext
<code>tiledb_timestamp</code>	Optional Datetime (POSIXct) for TileDB timestamp

---

<code>SOMADataFrameOpen</code>	<i>Open SOMA DataFrame</i>
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---

## Description

Factory function to open a SOMADataFrame for reading, (lifecycle: experimental)

## Usage

```
SOMADataFrameOpen(
    uri,
    mode = "READ",
    platform_config = NULL,
    tiledbsoma_ctx = NULL,
    tiledb_timestamp = NULL
)
```

## Arguments

uri	URI for the TileDB object
mode	One of "READ" or "WRITE"
platform_config	Optional platform configuration
tiledbsoma_ctx	Optional SOMATileDBContext
tiledb_timestamp	Optional Datetime (POSIXct) for TileDB timestamp

---

<code>SOMADenseNDArray</code>	<i>SOMADenseNDArray</i>
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---

## Description

SOMADenseNDArray is a dense, N-dimensional array of primitive type, with offset (zero-based) int64 integer indexing on each dimension with domain [0, maxInt64). The SOMADenseNDArray has a user-defined schema, which includes:

- **type:** a primitive type, expressed as an Arrow type (e.g., int64, float32, etc), indicating the type of data contained within the array
- **shape:** the shape of the array, i.e., number and length of each dimension

All dimensions must have a positive, non-zero length, and there must be 1 or more dimensions.

The default "fill" value for SOMADenseNDArray is the zero or null value of the array type (e.g., Arrow.float32 defaults to 0.0).

The write method is currently limited to writing from 2-d matrices. (lifecycle: experimental)

## Super classes

```
tiledbsoma::TileDBObject -> tiledbsoma::TileDBArray -> tiledbsoma::SOMAArrayBase -> tiledbsoma::SOMADenseNDArray
```

## Methods

### Public methods:

- `SOMADenseNDArray$read_arrow_table()`
- `SOMADenseNDArray$read_dense_matrix()`
- `SOMADenseNDArray$write()`
- `SOMADenseNDArray$clone()`

**Method** `read_arrow_table()`: Read as an 'arrow::Table' (lifecycle: experimental)

*Usage:*

```
SOMADenseNDArray$read_arrow_table(  
  coords = NULL,  
  result_order = "auto",  
  log_level = "warn"  
)
```

*Arguments:*

`coords` Optional list of integer vectors, one for each dimension, with a length equal to the number of values to read. If `NULL`, all values are read. List elements can be named when specifying a subset of dimensions.

`result_order` Optional order of read results. This can be one of either "ROW\_MAJOR", "COL\_MAJOR", or "auto" (default).

`result_order` Optional order of read results. This can be one of either "ROW\_MAJOR", "COL\_MAJOR", or "auto" (default).

`log_level` Optional logging level with default value of "warn".

*Returns:* An `arrow::Table`.

**Method** `read_dense_matrix()`: Read as a dense matrix (lifecycle: experimental)

*Usage:*

```
SOMADenseNDArray$read_dense_matrix(  
  coords = NULL,  
  result_order = "ROW_MAJOR",  
  log_level = "warn"  
)
```

*Arguments:*

`coords` Optional list of integer vectors, one for each dimension, with a length equal to the number of values to read. If `NULL`, all values are read. List elements can be named when specifying a subset of dimensions.

`result_order` Optional order of read results. This can be one of either "ROW\_MAJOR", "COL\_MAJOR", or "auto" (default).

`result_order` Optional order of read results. This can be one of either "ROW\_MAJOR", "COL\_MAJOR", or "auto" (default).

`log_level` Optional logging level with default value of "warn".

*Returns:* A `matrix` object

**Method `write()`:** Write matrix data to the array. (lifecycle: experimental)

More general write methods for higher-dimensional array could be added.

*Usage:*

```
SOMADenseNDArray$write(values, coords = NULL)
```

*Arguments:*

`values` A `matrix`. Character dimension names are ignored because `SOMADenseNDArray`'s use integer indexing.

`coords` A list of integer vectors, one for each dimension, with a length equal to the number of values to write. If `NULL`, the default, the values are taken from the row and column names of `values`.

**Method `clone()`:** The objects of this class are cloneable with this method.

*Usage:*

```
SOMADenseNDArray$clone(deep = FALSE)
```

*Arguments:*

`deep` Whether to make a deep clone.

## SOMADenseNDArrayCreate

*Create SOMA Dense Nd Array*

## Description

Factory function to create a `SOMADenseNDArray` for writing, (lifecycle: experimental)

## Usage

```
SOMADenseNDArrayCreate(
  uri,
  type,
  shape,
  platform_config = NULL,
  tiledbsoma_ctx = NULL,
  tiledb_timestamp = NULL
)
```

**Arguments**

<code>uri</code>	URI for the TileDB object
<code>type</code>	An Arrow type defining the type of each element in the array.
<code>shape</code>	A vector of integers defining the shape of the array.
<code>platform_config</code>	Optional platform configuration
<code>tiledbsoma_ctx</code>	Optional SOMATileDBContext
<code>tiledb_timestamp</code>	Optional Datetime (POSIXct) for TileDB timestamp

`SOMADenseNDArrayOpen`    *Open SOMA Dense Nd Array*

**Description**

Factory function to open a SOMADenseNDArray for reading, (lifecycle: experimental)

**Usage**

```
SOMADenseNDArrayOpen(
    uri,
    mode = "READ",
    platform_config = NULL,
    tiledbsoma_ctx = NULL,
    tiledb_timestamp = NULL
)
```

**Arguments**

<code>uri</code>	URI for the TileDB object
<code>mode</code>	One of "READ" or "WRITE"
<code>platform_config</code>	Optional platform configuration
<code>tiledbsoma_ctx</code>	Optional SOMATileDBContext
<code>tiledb_timestamp</code>	Optional Datetime (POSIXct) for TileDB timestamp

---

SOMAExperiment

*SOMA Experiment*

---

## Description

SOMAExperiment is a specialized [SOMACollection](#), representing one or more modes of measurement across a single collection of cells (aka a "multimodal dataset") with pre-defined fields: obs and ms (see *Active Bindings* below for details). (lifecycle: experimental)

## Adding new objects to a collection

The [SOMAExperiment](#) class provides a number of type-specific methods for adding new a object to the collection, such as `add_new_sparse_ndarray()` and `add_new_dataframe()`. These methods will create the new object and add it as member of the SOMAExperiment. The new object will always inherit the parent context (see [SOMATileDBContext](#)) and, by default, its platform configuration (see [PlatformConfig](#)). However, the user can override the default platform configuration by passing a custom configuration to the `platform_config` argument.

## Super classes

`tiledbsoma::TileDBObject -> tiledbsoma::TileDBGroup -> tiledbsoma::SOMACollectionBase -> SOMAExperiment`

## Active bindings

obs a [SOMADataFrame](#) containing primary annotations on the observation axis. The contents of the `soma_joinid` column define the observation index domain, `obs_id`. All observations for the SOMAExperiment must be defined in this dataframe.

ms a [SOMACollection](#) of named [SOMAMeasurements](#).

## Methods

### Public methods:

- [SOMAExperiment\\$axis\\_query\(\)](#)
- [SOMAExperiment\\$update\\_obs\(\)](#)
- [SOMAExperiment\\$update\\_var\(\)](#)
- [SOMAExperiment\\$clone\(\)](#)

**Method** `axis_query()`: Subset and extract data from a [SOMAMeasurement](#) by querying the obs/var axes.

*Usage:*

`SOMAExperiment$axis_query(measurement_name, obs_query = NULL, var_query = NULL)`

*Arguments:*

`measurement_name` The name of the measurement to query.

`obs_query, var_query` An [SOMAAxisQuery](#) object for the obs/var axis.

*Returns:* A [SOMAExperimentAxisQuery](#) object.

**Method update\_obs():** Update the obs [SOMADataFrame](#) to add or remove columns. See [SOMADataFrame\\$update\(\)](#) for details.

*Usage:*

```
SOMAExperiment$update_obs(values, row_index_name = NULL)
```

*Arguments:*

`values` A `data.frame`, [arrow::Table](#), or [arrow::RecordBatch](#).

`row_index_name` An optional scalar character. If provided, and if the `values` argument is a `data.frame` with row names, then the row names will be extracted and added as a new column to the `data.frame` prior to performing the update. The name of this new column will be set to the value specified by `row_index_name`.

**Method update\_var():** Update the var [SOMADataFrame](#) to add or remove columns. See [SOMADataFrame\\$update\(\)](#) for details.

*Usage:*

```
SOMAExperiment$update_var(values, measurement_name, row_index_name = NULL)
```

*Arguments:*

`values` A `data.frame`, [arrow::Table](#), or [arrow::RecordBatch](#).

`measurement_name` The name of the [SOMAMeasurement](#) whose var will be updated.

`row_index_name` An optional scalar character. If provided, and if the `values` argument is a `data.frame` with row names, then the row names will be extracted and added as a new column to the `data.frame` prior to performing the update. The name of this new column will be set to the value specified by `row_index_name`.

**Method clone():** The objects of this class are cloneable with this method.

*Usage:*

```
SOMAExperiment$clone(deep = FALSE)
```

*Arguments:*

`deep` Whether to make a deep clone.

## SOMAExperimentAxisQuery

### *SOMAExperiment Axis Query*

## Description

Perform an axis-based query against a [SOMAExperiment](#).

`SOMAExperimentAxisQuery` allows easy selection and extraction of data from a single [SOMAMeasurement](#) in a [SOMAExperiment](#), by obs/var (axis) coordinates and/or value filter. The primary use for this class is slicing [SOMAExperiment](#) X layers by obs or var value and/or coordinates. (lifecycle: experimental)

**X Layer Support:**

Slicing on `SOMASparseNDArray` X matrices is supported; slicing on `SOMADenseNDArray` is not supported at this time.

**Result Size:**

`SOMAExperimentAxisQuery` query class assumes it can store the full result of both axis dataframe queries in memory, and only provides incremental access to the underlying X NDArray. Accessors such as `n_obs` and `n_vars` codify this in the class.

**Active bindings**

- `experiment` The parent `SOMAExperiment` object.
- `indexer` The `SOMAAxisIndexer` object.
- `obs_query` The obs `SOMAAxisQuery` object.
- `var_query` The var `SOMAAxisQuery` object.
- `n_obs` The number of obs axis query results.
- `n_vars` The number of var axis query results.
- `obs_df` The obs `SOMADataFrame` object.
- `var_df` The var `SOMADataFrame` object for the specified `measurement_name`.
- `ms` The `SOMAMeasurement` object for the specified `measurement_name`.

**Methods****Public methods:**

- `SOMAExperimentAxisQuery$new()`
- `SOMAExperimentAxisQuery$obs()`
- `SOMAExperimentAxisQuery$var()`
- `SOMAExperimentAxisQuery$obs_joinids()`
- `SOMAExperimentAxisQuery$var_joinids()`
- `SOMAExperimentAxisQuery$X()`
- `SOMAExperimentAxisQuery$read()`
- `SOMAExperimentAxisQuery$to_sparse_matrix()`
- `SOMAExperimentAxisQuery$to_seurat()`
- `SOMAExperimentAxisQuery$to_seurat_assay()`
- `SOMAExperimentAxisQuery$to_seurat_reduction()`
- `SOMAExperimentAxisQuery$to_seurat_graph()`
- `SOMAExperimentAxisQuery$to_single_cell_experiment()`
- `SOMAExperimentAxisQuery$clone()`

**Method** `new()`: Create a new `SOMAExperimentAxisQuery` object.

*Usage:*

```
SOMAExperimentAxisQuery$new(
  experiment,
  measurement_name,
  obs_query = NULL,
  var_query = NULL
)
Arguments:
experiment A SOMAExperiment object.
measurement_name The name of the measurement to query.
obs_query, var_query An SOMAAxisQuery object for the obs/var axis.
```

**Method** obs(): Retrieve obs [TableReadIter](#)

*Usage:*

```
SOMAExperimentAxisQuery$obs(column_names = NULL)
```

*Arguments:*

column\_names A character vector of column names to retrieve

**Method** var(): Retrieve var [arrow::Table](#)

*Usage:*

```
SOMAExperimentAxisQuery$var(column_names = NULL)
```

*Arguments:*

column\_names A character vector of column names to retrieve

**Method** obs\_joinids(): Retrieve soma\_joinids as an [arrow::Array](#) for obs.

*Usage:*

```
SOMAExperimentAxisQuery$obs_joinids()
```

**Method** var\_joinids(): Retrieve soma\_joinids as an [arrow::Array](#) for var.

*Usage:*

```
SOMAExperimentAxisQuery$var_joinids()
```

**Method** X(): Retrieves an X layer as a [linkSOMASparseNDArrayRead](#)

*Usage:*

```
SOMAExperimentAxisQuery$X(layer_name)
```

*Arguments:*

layer\_name The name of the layer to retrieve.

**Method** read(): Reads the entire query result as a list of [arrow::Tables](#). This is a low-level routine intended to be used by loaders for other in-core formats, such as Seurat, which can be created from the resulting Tables.

*Usage:*

```
SOMAExperimentAxisQuery$read(
  X_layers = NULL,
  obs_column_names = NULL,
  var_column_names = NULL
)
```

*Arguments:*

`X_layers` The name(s) of the X layer(s) to read and return.  
`obs_column_names, var_column_names` Specify which column names in `var` and `obs` dataframes to read and return.

**Method `to_sparse_matrix()`:** Retrieve a collection layer as a sparse matrix with named dimensions.

Load any layer from the `X`, `obsm`, `varm`, `obsp`, or `varp` collections as a [sparse matrix](#).

By default the matrix dimensions are named using the `soma_joinid` values in the specified layer's dimensions (e.g., `soma_dim_0`). However, dimensions can be named using values from any `obs` or `var` column that uniquely identifies each record by specifying the `obs_index` and `var_index` arguments.

For layers in `obsm` or `varm`, the column axis (the axis not indexed by "obs" or "var") is set to the range of values present in "soma\_dim\_1"; this ensures that gaps in this axis are preserved (eg. when a query for "obs" that results in selecting entries that are all zero for a given PC)

*Usage:*

```
SOMAExperimentAxisQuery$to_sparse_matrix(
  collection,
  layer_name,
  obs_index = NULL,
  var_index = NULL
)
```

*Arguments:*

`collection` The [SOMACollection](#) containing the layer of interest, either: "`X`", "`obsm`", "`varm`", "`obsp`", or "`varp`".

`layer_name` Name of the layer to retrieve from the collection.

`obs_index, var_index` Name of the column in `obs` or `var` (`var_index`) containing values that should be used as dimension labels in the resulting matrix. Whether the values are used as row or column labels depends on the selected collection:

Collection	<code>obs_index</code>	<code>var_index</code>
<code>X</code>	row names	column names
<code>obsm</code>	row names	ignored
<code>varm</code>	ignored	row names
<code>obsp</code>	row and column names	ignored
<code>varp</code>	ignored	row and column names

*Returns:* A [Matrix:::sparseMatrix](#)

**Method `to_seurat()`:** Loads the query as a [Seurat](#) object

*Usage:*

```
SOMAExperimentAxisQuery$to_seurat(
  X_layers = c(counts = "counts", data = "logcounts"),
  obs_index = NULL,
  var_index = NULL,
```

```

obs_column_names = NULL,
var_column_names = NULL,
obsm_layers = NULL,
varm_layers = NULL,
obsp_layers = NULL
)

```

*Arguments:*

`X_layers` A named character of X layers to add to the Seurat assay where the names are the names of Seurat slots and the values are the names of layers within X; names should be one of:

- “counts” to add the layer as counts
- “data” to add the layer as data
- “scale.data” to add the layer as scale.data

At least one of “counts” or “data” is required

`obs_index` Name of column in obs to add as cell names; uses `paste0("cell", obs_joinids())` by default

`var_index` Name of column in var to add as feature names; uses `paste0("feature", var_joinids())` by default

`obs_column_names` Names of columns in obs to add as cell-level meta data; by default, loads all columns

`var_column_names` Names of columns in var to add as feature-level meta data; by default, loads all columns

`obsm_layers` Names of arrays in obsm to add as the cell embeddings; pass FALSE to suppress loading in any dimensional reductions; by default, loads all dimensional reduction information

`varm_layers` Named vector of arrays in varm to load in as the feature loadings; names must be names of arrays in obsm (eg. `varm_layers = c(X_pca = "PCs")`); pass FALSE to suppress loading in any feature loadings; will try to determine varm\_layers from obsm\_layers

`obsp_layers` Names of arrays in obsp to load in as [Graphs](#); by default, loads all graphs

*Returns:* A [Seurat](#) object

**Method to\_seurat\_assay():** Loads the query as a Seurat [Assay](#)

*Usage:*

```

SOMAExperimentAxisQuery$to_seurat_assay(
  X_layers = c(counts = "counts", data = "logcounts"),
  obs_index = NULL,
  var_index = NULL,
  var_column_names = NULL
)

```

*Arguments:*

`X_layers` A named character of X layers to add to the Seurat assay where the names are the names of Seurat slots and the values are the names of layers within X; names should be one of:

- “counts” to add the layer as counts
- “data” to add the layer as data

- “scale.data” to add the layer as scale.data

At least one of “counts” or “data” is required

```
obs_index Name of column in obs to add as cell names; uses paste0("cell", obs_joinids())
by default
var_index Name of column in var to add as feature names; uses paste0("feature", var_joinids())
by default
var_column_names Names of columns in var to add as feature-level meta data; by default,
loads all columns
```

*Returns:* An [Assay](#) object

**Method to\_seurat\_reduction():** Loads the query as a Seurat [dimensional reduction](#)

*Usage:*

```
SOMAExperimentAxisQuery$to_seurat_reduction(
  obsm_layer,
  varm_layer = NULL,
  obs_index = NULL,
  var_index = NULL
)
```

*Arguments:*

obsm\_layer Name of array in obsm to load as the cell embeddings

varm\_layer Name of the array in varm to load as the feature loadings; by default, will try to determine varm\_layer from obsm\_layer

```
obs_index Name of column in obs to add as cell names; uses paste0("cell", obs_joinids())
by default
```

```
var_index Name of column in var to add as feature names; uses paste0("feature", var_joinids())
by default
```

*Returns:* A [DimReduc](#) object

**Method to\_seurat\_graph():** Loads the query as a Seurat [graph](#)

*Usage:*

```
SOMAExperimentAxisQuery$to_seurat_graph(obsp_layer, obs_index = NULL)
```

*Arguments:*

obsp\_layer Name of array in obsp to load as the graph

```
obs_index Name of column in obs to add as cell names; uses paste0("cell", obs_joinids())
by default
```

*Returns:* A [Graph](#) object

**Method to\_single\_cell\_experiment():** Loads the query as a [SingleCellExperiment](#) object

*Usage:*

```
SOMAExperimentAxisQuery$to_single_cell_experiment(
  X_layers = NULL,
  obs_index = NULL,
  var_index = NULL,
  obs_column_names = NULL,
```

```

    var_column_names = NULL,
    obsm_layers = NULL,
    obsp_layers = NULL,
    varp_layers = NULL
)

```

*Arguments:*

X\_layers A character vector of X layers to add as assays in the main experiment; may optionally be named to set the name of the resulting assay (eg. X\_layers = c(counts = "raw") will load in X layer “raw” as assay “counts”); by default, loads in all X layers  
obs\_index Name of column in obs to add as cell names; uses paste0("cell", obs\_joinids()) by default  
var\_index Name of column in var to add as feature names; uses paste0("feature", var\_joinids()) by default  
obs\_column\_names Names of columns in obs to add as colData; by default, loads all columns  
var\_column\_names Names of columns in var to add as rowData; by default, loads all columns  
obsm\_layers Names of arrays in obsm to add as the reduced dimensions; pass FALSE to suppress loading in any reduced dimensions; by default, loads all reduced dimensions  
obsp\_layers Names of arrays in obsp to load in as [SelfHits](#); by default, loads all graphs  
varp\_layers Names of arrays in varp to load in as [SelfHits](#); by default, loads all networks

*Returns:* A [SingleCellExperiment](#) object

**Method clone():** The objects of this class are cloneable with this method.

*Usage:*

```
SOMAExperimentAxisQuery$clone(deep = FALSE)
```

*Arguments:*

deep Whether to make a deep clone.

SOMAExperimentCreate *Create SOMA Experiment*

## Description

Factory function to create a SOMADataFrame for writing, (lifecycle: experimental)

## Usage

```

SOMAExperimentCreate(
  uri,
  platform_config = NULL,
  tiledbsoma_ctx = NULL,
  tiledb_timestamp = NULL
)

```

## Arguments

uri	URI for the TileDB object
platform_config	Optional platform configuration
tiledbsoma_ctx	Optional SOMATileDBContext
tiledb_timestamp	Optional Datetime (POSIXct) for TileDB timestamp

---

SOMAExperimentOpen     *Open SOMA Experiment*

---

## Description

Factory function to open a SOMAExperiment for reading, (lifecycle: experimental)

## Usage

```
SOMAExperimentOpen(  
    uri,  
    mode = "READ",  
    platform_config = NULL,  
    tiledbsoma_ctx = NULL,  
    tiledb_timestamp = NULL  
)
```

## Arguments

uri	URI for the TileDB object
mode	One of "READ" or "WRITE"
platform_config	Optional platform configuration
tiledbsoma_ctx	optional SOMATileDBContext
tiledb_timestamp	Optional Datetime (POSIXct) for TileDB timestamp. In READ mode, defaults to the current time. If non-NULL, then all members accessed through the collection object inherit the timestamp.

## Description

A SOMAMeasurement is a sub-element of a [SOMAExperiment](#), and is otherwise a specialized [SOMACollection](#) with pre-defined fields: X, var, obsm/varm, and obsp/varp (see *Active Bindings* below for details). (lifecycle: experimental)

## Adding new objects to a collection

The [SOMAMeasurement](#) class provides a number of type-specific methods for adding new object to the collection, such as `add_new_sparse_ndarray()` and `add_new_dataframe()`. These methods will create the new object and add it as member of the [SOMAMeasurement](#). The new object will always inherit the parent context (see [SOMATileDBContext](#)) and, by default, its platform configuration (see [PlatformConfig](#)). However, the user can override the default platform configuration by passing a custom configuration to the `platform_config` argument.

## Super classes

```
tiledbsoma::TileDBObject -> tiledbsoma::TileDBGroup -> tiledbsoma::SOMACollectionBase
-> SOMAMeasurement
```

## Active bindings

var a [SOMADataFrame](#) containing primary annotations on the variable axis, for variables in this measurement (i.e., annotates columns of X). The contents of the `soma_joinid` column define the variable index domain, `var_id`. All variables for this measurement must be defined in this dataframe.

X a [SOMACollection](#) of [SOMASparseNDArrays](#), each contains measured feature values indexed by `[obsid, varid]`.

obsm a [SOMACollection](#) of [SOMADenseNDArrays](#) containing annotations on the observation axis. Each array is indexed by `obsid` and has the same shape as `obs`.

obsp a [SOMACollection](#) of [SOMASparseNDArrays](#) containing pairwise annotations on the observation axis and indexed with `[obsid_1, obsid_2]`.

varm a [SOMACollection](#) of [SOMADenseNDArrays](#) containing annotations on the variable axis. Each array is indexed by `varid` and has the same shape as `var`.

varp a [SOMACollection](#) of [SOMASparseNDArrays](#) containing pairwise annotations on the variable axis and indexed with `[varid_1, varid_2]`.

## Methods

### Public methods:

- [SOMAMeasurement\\$clone\(\)](#)

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

```
SOMAMeasurement$clone(deep = FALSE)
```

*Arguments:*

deep Whether to make a deep clone.

SOMAMeasurementCreate *Create SOMA Measurement*

## Description

Factory function to create a SOMAMeasurement for writing, (lifecycle: experimental)

## Usage

```
SOMAMeasurementCreate(  
    uri,  
    platform_config = NULL,  
    tiledbsoma_ctx = NULL,  
    tiledb_timestamp = NULL  
)
```

## Arguments

uri	URI for the TileDB object
platform_config	Optional platform configuration
tiledbsoma_ctx	Optional SOMATileDBContext
tiledb_timestamp	Optional Datetime (POSIXct) for TileDB timestamp

SOMAMeasurementOpen *Open SOMA Measurement*

## Description

Factory function to open a SOMAMeasurement for reading, (lifecycle: experimental)

## Usage

```
SOMAMeasurementOpen(  
    uri,  
    mode = "READ",  
    platform_config = NULL,  
    tiledbsoma_ctx = NULL,  
    tiledb_timestamp = NULL  
)
```

## Arguments

uri	URI for the TileDB object
mode	One of "READ" or "WRITE"
platform_config	Optional platform configuration
tiledbsoma_ctx	optional SOMATileDBContext
tiledb_timestamp	Optional Datetime (POSIXct) for TileDB timestamp. In READ mode, defaults to the current time. If non-NULL, then all members accessed through the collection object inherit the timestamp.

SOMAOpen

*Open a SOMA Object*

## Description

Utility function to open the corresponding SOMA Object given a URI, (lifecycle: experimental)

## Usage

```
SOMAOpen(
    uri,
    mode = "READ",
    platform_config = NULL,
    tiledbsoma_ctx = NULL,
    tiledb_timestamp = NULL
)
```

## Arguments

uri	URI for the TileDB object
mode	One of "READ" or "WRITE"
platform_config	Optional platform configuration
tiledbsoma_ctx	Optional SOMATileDBContext
tiledb_timestamp	Optional Datetime (POSIXct) with TileDB timestamp. For SOMACollections, all accessed members inherit the collection opening timestamp, and in READ mode the collection timestamp defaults to the time of opening.

---

SOMASparseNDArray	<i>SOMASparseNDArray</i>	
-------------------	--------------------------	--

---

## Description

`SOMASparseNDArray` is a sparse, N-dimensional array with offset (zero-based) integer indexing on each dimension. The `SOMASparseNDArray` has a user-defined schema, which includes:

- type - a primitive type, expressed as an Arrow type (e.g., `int64`, `float32`, etc)
- shape - the shape of the array, i.e., number and length of each dimension

All dimensions must have a positive, non-zero length.

**Note** - on TileDB this is a sparse array with N `int64` dimensions of domain [0, `maxInt64`), and a single attribute.

### Duplicate writes:

As duplicate index values are not allowed, index values already present in the object are overwritten and new index values are added. (lifecycle: experimental)

## Super classes

```
tiledbsoma::TileDBObject -> tiledbsoma::TileDBArray -> tiledbsoma::SOMAArrayBase -> tiledbsoma::SOMANDBase -> SOMASparseNDArray
```

## Methods

### Public methods:

- `SOMASparseNDArray$read()`
- `SOMASparseNDArray$write()`
- `SOMASparseNDArray$nnz()`
- `SOMASparseNDArray$clone()`

**Method** `read()`: Reads a user-defined slice of the `SOMASparseNDArray`

*Usage:*

```
SOMASparseNDArray$read(
  coords = NULL,
  result_order = "auto",
  log_level = "auto"
)
```

*Arguments:*

`coords` Optional list of integer vectors, one for each dimension, with a length equal to the number of values to read. If `NULL`, all values are read. List elements can be named when specifying a subset of dimensions.

`result_order` Optional order of read results. This can be one of either `"ROW_MAJOR"`, `"COL_MAJOR"`, or `"auto"` (default).

`log_level` Optional logging level with default value of "warn".  
`iterated` Option boolean indicated whether data is read in call (when FALSE, the default value) or in several iterated steps.

*Returns:* [SOMASparseNDArrayRead](#)

**Method** `write()`: Write matrix-like data to the array. (lifecycle: experimental)

*Usage:*

```
SOMASparseNDArray$write(values, bbox = NULL)
```

*Arguments:*

`values` Any matrix-like object coercible to a [TsparseMatrix](#). Character dimension names are ignored because SOMANDArray's use integer indexing.

`bbox` A vector of integers describing the upper bounds of each dimension of `values`. Generally should be NULL.

**Method** `nnz()`: Retrieve number of non-zero elements (lifecycle: experimental)

*Usage:*

```
SOMASparseNDArray$nnz()
```

*Returns:* A scalar with the number of non-zero elements

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

```
SOMASparseNDArray$clone(deep = FALSE)
```

*Arguments:*

`deep` Whether to make a deep clone.

## SOMASparseNDArrayCreate

*Create SOMA Sparse Nd Array*

### Description

Factory function to create a SOMASparseNDArray for writing, (lifecycle: experimental)

### Usage

```
SOMASparseNDArrayCreate(  
  uri,  
  type,  
  shape,  
  platform_config = NULL,  
  tiledbsoma_ctx = NULL,  
  tiledb_timestamp = NULL  
)
```

## Arguments

<code>uri</code>	URI for the TileDB object
<code>type</code>	An Arrow type defining the type of each element in the array.
<code>shape</code>	A vector of integers defining the shape of the array.
<code>platform_config</code>	Optional platform configuration
<code>tiledbsoma_ctx</code>	Optional SOMATileDBContext
<code>tiledb_timestamp</code>	Optional Datetime (POSIXct) for TileDB timestamp

`SOMASparseNDArrayOpen` *Open SOMA Sparse Nd Array*

## Description

Factory function to open a SOMASparseNDArray for reading, (lifecycle: experimental)

## Usage

```
SOMASparseNDArrayOpen(
    uri,
    mode = "READ",
    platform_config = NULL,
    tiledbsoma_ctx = NULL,
    tiledb_timestamp = NULL
)
```

## Arguments

<code>uri</code>	URI for the TileDB object
<code>mode</code>	One of "READ" or "WRITE"
<code>platform_config</code>	Optional platform configuration
<code>tiledbsoma_ctx</code>	Optional SOMATileDBContext
<code>tiledb_timestamp</code>	Optional Datetime (POSIXct) for TileDB timestamp

---

SOMATileDBContext      *SOMA TileDB Context*

---

## Description

Context map for TileDB-backed SOMA objects

## Super classes

`tiledbsoma::MappingBase -> tiledbsoma::ScalarMap -> tiledbsoma::SOMAContextBase ->`  
SOMATileDBContext

## Methods

### Public methods:

- `SOMATileDBContext$new()`
- `SOMATileDBContext$keys()`
- `SOMATileDBContext$items()`
- `SOMATileDBContext$length()`
- `SOMATileDBContext$get()`
- `SOMATileDBContext$set()`
- `SOMATileDBContext$to_tiledb_context()`
- `SOMATileDBContext$context()`
- `SOMATileDBContext$clone()`

#### Method `new()`:

*Usage:*

`SOMATileDBContext$new(config = NULL, cached = TRUE)`

*Arguments:*

`config` ...

`cached` Force new creation

*Returns:* An instantiated SOMATileDBContext object

#### Method `keys()`:

*Usage:*

`SOMATileDBContext$keys()`

*Returns:* The keys of the map

#### Method `items()`:

*Usage:*

`SOMATileDBContext$items()`

*Returns:* Return the items of the map as a list

**Method** length():*Usage:*

SOMATileDBContext\$length()

*Returns:* The number of items in the map**Method** get():*Usage:*

SOMATileDBContext\$get(key, default = quote(expr = ))

*Arguments:*

key Key to fetch

default Default value to fetch if key is not found; defaults to NULL

*Returns:* The value of key in the map, or default if key is not found**Method** set():*Usage:*

SOMATileDBContext\$set(key, value)

*Arguments:*

key Key to set

value Value to add for key, or NULL to remove the entry for key

*Returns:* [chainable] Invisibly returns self with value added as key**Method** to\_tiledb\_context():*Usage:*

SOMATileDBContext\$to\_tiledb\_context()

*Returns:* A [tiledb\\_ctx](#) object, dynamically constructed. Most useful for the constructor of this class.**Method** context():*Usage:*

SOMATileDBContext\$context()

*Returns:* A [tiledb\\_ctx](#) object, which is a stored (and long-lived) result from to\_tiledb\_context.**Method** clone(): The objects of this class are cloneable with this method.*Usage:*

SOMATileDBContext\$clone(deep = FALSE)

*Arguments:*

deep Whether to make a deep clone.

SparseReadIter

*SparseReadIter***Description**

`SparseReadIter` is a class that allows for iteration over a reads on `SOMASparseNDArray`. Iteration chunks are retrieved as 0-based Views `matrixZeroBasedView` of `Matrix::sparseMatrix`.

**Super class**

`tiledbsoma::ReadIter` -> `SparseReadIter`

**Methods****Public methods:**

- `SparseReadIter$new()`
- `SparseReadIter$concat()`
- `SparseReadIter$clone()`

**Method** `new()`: Create (lifecycle: experimental)

*Usage:*

`SparseReadIter$new(sr, shape, zero_based = FALSE)`

*Arguments:*

`sr` Soma reader pointer

`shape` Shape of the full matrix

`zero_based` Logical, if TRUE will make iterator for `Matrix::dgTMatrix-class` otherwise `matrixZeroBasedView`.

**Method** `concat()`: Concatenate remainder of iterator.

*Usage:*

`SparseReadIter$concat()`

*Returns:* `matrixZeroBasedView` of `Matrix::sparseMatrix`

**Method** `clone()`: The objects of this class are cloneable with this method.

*Usage:*

`SparseReadIter$clone(deep = FALSE)`

*Arguments:*

`deep` Whether to make a deep clone.

---

TableReadIter	<i>SOMA Read Iterator over Arrow Table</i>
---------------	--

---

## Description

TableReadIter is a class that allows for iteration over a reads on SOMASparseNDArray and SOMADataFrame. Iteration chunks are retrieved as arrow::Table

## Super class

`tiledbsoma::ReadIter` -> TableReadIter

## Methods

### Public methods:

- `TableReadIter$concat()`
- `TableReadIter$clone()`

**Method concat():** Concatenate remainder of iterator.

*Usage:*

`TableReadIter$concat()`

*Returns:* arrow::Table

**Method clone():** The objects of this class are cloneable with this method.

*Usage:*

`TableReadIter$clone(deep = FALSE)`

*Arguments:*

`deep` Whether to make a deep clone.

---

TileDBObject	<i>TileDB Object Base Class</i>
--------------	---------------------------------

---

## Description

Base class to implement shared functionality across the TileDBArray and TileDBGroup classes.  
(lifecycle: experimental)

## Active bindings

`platform_config` Platform configuration  
`tiledbsoma_ctx` SOMATileDBContext  
`uri` The URI of the TileDB object.

## Methods

### Public methods:

- `TileDBObject$new()`
- `TileDBObject$class()`
- `TileDBObject$is_open()`
- `TileDBObject$mode()`
- `TileDBObject$print()`
- `TileDBObject$exists()`
- `TileDBObject$clone()`

**Method** `new():` Create a new TileDB object. (lifecycle: experimental)

*Usage:*

```
TileDBObject$new(
  uri,
  platform_config = NULL,
  tiledbsoma_ctx = NULL,
  tiledb_timestamp = NULL,
  internal_use_only = NULL
)
```

*Arguments:*

`uri` URI for the TileDB object

`platform_config` Optional platform configuration

`tiledbsoma_ctx` Optional SOMATileDBContext

`tiledb_timestamp` Optional Datetime (POSIXct) with TileDB timestamp

`internal_use_only` Character value to signal this is a 'permitted' call, as `new()` is considered internal and should not be called directly.

**Method** `class():` Print the name of the R6 class.

*Usage:*

```
TileDBObject$class()
```

**Method** `is_open():` Determine if the object is open for reading or writing

*Usage:*

```
TileDBObject$is_open()
```

*Returns:* TRUE if the object is open, otherwise FALSE

**Method** `mode():` Get the mode of the object

*Usage:*

```
TileDBObject$mode()
```

*Returns:* If the object is closed, returns "CLOSED"; otherwise returns the mode (eg. "READ") of the object

**Method** `print():` Print-friendly representation of the object.

*Usage:*

```
TileDBObject$print()
```

**Method exists():** Check if the object exists. (lifecycle: experimental)

*Usage:*

```
TileDBObject$exists()
```

*Returns:* TRUE`` if the object exists, FALSE` otherwise.

**Method clone():** The objects of this class are cloneable with this method.

*Usage:*

```
TileDBObject$clone(deep = FALSE)
```

*Arguments:*

deep Whether to make a deep clone.

---

tiledbsoma_stats	<i>TileDB SOMA statistics</i>
------------------	-------------------------------

---

## Description

These functions expose the TileDB Core functionality for performance measurements and statistics.

## Usage

```
tiledbsoma_stats_enable()
```

```
tiledbsoma_stats_disable()
```

```
tiledbsoma_stats_reset()
```

```
tiledbsoma_stats_dump()
```

```
tiledbsoma_stats_show()
```

## Details

- `tiledbsoma_stats_enable()/tiledbsoma_stats_disable()`: Enable and disable TileDB's internal statistics.
- `tiledbsoma_stats_reset()`: Reset all statistics to 0.
- `tiledbsoma_stats_dump()`: Dump all statistics to a JSON string.
- `tiledbsoma_stats_show()`: Print all statistics to the console.

`write_soma`*Write a SOMA Object from an R Object*

## Description

Convert R objects to their appropriate SOMA counterpart function and methods can be written for it to provide a high-level R → SOMA interface

## Usage

```
write_soma(x, uri, ..., platform_config = NULL, tiledbsoma_ctx = NULL)
```

## Arguments

<code>x</code>	An object
<code>uri</code>	URI for resulting SOMA object
<code>...</code>	Arguments passed to other methods
<code>platform_config</code>	Optional <a href="#">platform configuration</a>
<code>tiledbsoma_ctx</code>	Optional <a href="#">SOMATileDBContext</a>

## Value

The URI to the resulting [SOMAExperiment](#) generated from the data contained in `x`

## Known methods

- [Writing Seurat objects](#)
- [Writing SummarizedExperiment objects](#)
- [Writing SingleCellExperiment objects](#)

`write_soma.Seurat`*Write a Seurat object to a SOMA*

## Description

Write a [Seurat](#) object to a SOMA

## Usage

```
## S3 method for class 'Seurat'
write_soma(x, uri, ..., platform_config = NULL, tiledbsoma_ctx = NULL)
```

## Arguments

x	A <a href="#">Seurat</a> object
uri	URI for resulting SOMA object
...	Arguments passed to other methods
platform_config	Optional <a href="#">platform configuration</a>
tiledbsoma_ctx	Optional <a href="#">SOMATileDBContext</a>

## Value

The URI to the resulting [SOMAExperiment](#) generated from the data contained in x

## Writing Cell-Level Meta Data

Cell-level meta data is written out as a [data frame](#) called “obs” at the [experiment](#) level

## Writing Assays

[Seurat Assay](#) objects are written out as individual [measurements](#):

- the “data” matrix is written out a [sparse matrix](#) called “data” within the “X” group
- the “counts” matrix, if not [empty](#), is written out a [sparse matrix](#) called “counts” within the “X” group
- the “scale.data” matrix, if not [empty](#), is written out a [sparse matrix](#) called “scale\_data” within the “X” group
- feature-level meta data is written out as a [data frame](#) called “var”

Expression matrices are transposed (cells as rows) prior to writing. All other slots, including results from extended assays (eg. [SCTAssay](#), [ChromatinAssay](#)) are lost

## Writing DimReducs

[Seurat DimReduc](#) objects are written out to the “obsm” and “varm” groups of a [measurement](#):

- cell embeddings are written out as a [sparse matrix](#) in the “obsm” group
- feature loadings, if not [empty](#), are written out as a [sparse matrix](#) in the “varm” groups; loadings are padded with NAs to include all features

Dimensional reduction names are translated to AnnData-style names (eg. “pca” becomes X\_pca for embeddings and “PCs” for loadings). All other slots, including projected feature loadings and jackstraw information, are lost

## Writing Graphs

[Seurat Graph](#) objects are written out as [sparse matrices](#) to the “obsp” group of a [measurement](#)

## Writing SeuratCommands

[Seurat command](#) logs are written out as [data frames](#) to the “seurat\_commands” group of a [collection](#)

`write_soma.SingleCellExperiment`

*Write a [SingleCellExperiment](#) object to a SOMA*

## Description

Write a [SingleCellExperiment](#) object to a SOMA

## Usage

```
## S3 method for class 'SingleCellExperiment'
write_soma(
  x,
  uri,
  ms_name = NULL,
  ...,
  platform_config = NULL,
  tiledbsoma_ctx = NULL
)
```

## Arguments

<code>x</code>	An object
<code>uri</code>	URI for resulting SOMA object
<code>ms_name</code>	Name for resulting measurement; defaults to <a href="#">mainExpName(x)</a>
<code>...</code>	Arguments passed to other methods
<code>platform_config</code>	Optional <a href="#">platform configuration</a>
<code>tiledbsoma_ctx</code>	Optional <a href="#">SOMATileDBContext</a>

## Value

The URI to the resulting [SOMAExperiment](#) generated from the data contained in `x`

## Writing Reduced Dimensions

Reduced dimensions are written out as [sparse matrices](#) within the `obsm` group of [measurement](#) names `ms_name`

## Writing Column Pairs

Column-wise relationship matrices are written out as [sparse matrices](#) within the `obsp` group of [measurement](#) names `ms_name`

### Writing Row Pairs

Row-wise relationship matrices are written out as [sparse matrices](#) within the varp group of [measurement names](#) ms\_name

### Writing colData

colData is written out as a [data frame](#) called “obs” at the [experiment](#) level

### Writing Assay Matrices

Each [assay matrix](#) is written out as a [sparse matrix](#) within the X group of [measurement names](#) ms\_name. Names for assay matrices within X are taken from the [assay names](#). Assay matrices are transposed (samples as rows) prior to writing

### Writing rowData

rowData is written out as a [data frame](#) called “var” at the [measurement](#) level

---

```
write_soma.SummarizedExperiment
```

*Write a SummarizedExperiment object to a SOMA*

---

## Description

Write a [SummarizedExperiment](#) object to a SOMA

## Usage

```
## S3 method for class 'SummarizedExperiment'  
write_soma(x, uri, ms_name, ..., platform_config = NULL, tiledbsoma_ctx = NULL)
```

## Arguments

x	An object
uri	URI for resulting SOMA object
ms_name	Name for resulting measurement
...	Arguments passed to other methods
platform_config	Optional <a href="#">platform configuration</a>
tiledbsoma_ctx	Optional <a href="#">SOMATileDBContext</a>

## Value

The URI to the resulting [SOMAExperiment](#) generated from the data contained in x

**Writing colData**

colData is written out as a **data frame** called “obs” at the **experiment** level

**Writing Assay Matrices**

Each **assay matrix** is written out as a **sparse matrix** within the X group of **measurement** names ms\_name. Names for assay matrices within X are taken from the **assay names**. Assay matrices are transposed (samples as rows) prior to writing

**Writing rowData**

rowData is written out as a **data frame** called “var” at the **measurement** level

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